

# Discharge measurement structures

Third revised edition

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### 3.3 Properties and limits of application of structures

#### 3.3.1 General

In Section 3.2 the most common demands made upon discharge measuring or regulating structures are described. In Chapters 4 to 9, the properties and limits of application of each separate structure are given in the sections entitled Description and Limits of application. To aid the design engineer in selecting a suitable structure, we have tabulated the most relevant data.

#### 3.3.2 Tabulation of data

Table 3.1 consists of 18 columns giving data on the following subjects

- Column 1 – Name of the standard discharge measuring or regulating device. In brackets is the section number in which the device is discussed. Each section generally consists of sub-sections entitled: Description, Evaluation of discharge, Modular limit, Limits of application.
- Column 2 – A three-dimensional sketch of the structure.
- Column 3 – Shape of the control section perpendicular to the direction of flow and the related power  $u$  to which the head or differential head appears in the head-discharge equation.
- Column 4 – Possible function of the structure. If the area of the control section cannot be changed, the structure can only be used to measure discharges; this is indicated by the letter M in the column. If the weir crest can be made movable by use of a gate arrangement as shown in Section 4.2, or if the area of an orifice is variable, the structure can be used to measure and regulate discharges and has the letters MR in the column. The Dethridge and propeller meters can measure a flow rate in  $m^3/s$  and totalize the volume in  $m^3$ . The discharge can be regulated by a separate gate, which is, however, incorporated in the standard design. These two devices have the letters MRV in the column.
- Column 5 – Minimum value of  $H_1$  or  $\Delta h$  in metres or in terms of structural dimensions.
- Column 6 – As Column 5, but giving maximum values.
- Column 7 – Minimum height of weir crest or invert of orifice above approach channel bottom; in metres or in terms of structural dimensions.
- Column 8 – Minimum dimensions of control section;  $b_c$ ,  $B_c$ ,  $w$ , and  $D_p$ .
- Column 9 – Range of notch angle  $\theta$  for triangular control sections.
- Column 10 – Minimum discharge ( $Q_{min}$ ) in  $m^3/s \times 10^{-3}$  or  $l/s$  of the smallest possible structure of the relevant type, being determined by the minima given in Columns 5, 8, and 9.
- Column 11 – Maximum discharge:  $q$  in  $m^2/s$ , being the discharge per metre crest width if this width is not limited to a maximum value, or  $Q$  in  $m^3/s$  if both the head (differential) and control section dimensions are limited to a maximum. No maximum discharge value is shown if neither the head (differential) nor the control dimensions are limited by a theoretical maximum. Obviously, in such cases, the discharge is limited because of various practical and constructional reasons.

Column 12 – Value of  $\gamma = Q_{max}/Q_{min}$  of the structure. If  $Q_{max}$  cannot be calculated directly, the  $\gamma$ -value can usually be determined by substituting the limitations on head (differential) in the head-discharge equation, as shown in Section 3.2.3.

Column 13 – Modular limit  $H_2/H_1$  or required total head loss over the structure. The modular limit is defined as that submergence ratio  $H_2/H_1$  whereby the modular discharge is reduced by 1% due to an increasing tailwater level.

Column 14 – Error in the product  $C_d C_v$  or in the coefficient  $C_e$ .

Column 15 – Maximum value of the sensitivity of the structure times 100, being

$$100 S = \frac{u}{h_1} \Delta h_1 \cdot 100$$

where the minimum absolute value of  $h_1$  is used with the assumption  $\Delta h_1 = 0.01$  m. The figures shown give a percentage error in the minimum discharge if an error in the determination of  $h_1$  equal to 0.01 m is made. The actual error  $\Delta h$  obviously depends on the method by which the head is determined.

Column 16 – Classifies the structures as to the ease with which they pass floating and suspended debris.

Column 17 – Classifies the structures as to the ease with which they pass bed-load and suspended load.

Column 18 – Remarks.

### 3.4 Selecting the structure

Although it is possible to select a suitable structure by using Table 3.1, an engineer may need some assistance in selecting the most appropriate one. To help him in this task, we will try to illustrate the process of selection. To indicate the different stages in this process we shall use differently shaped blocks, with connecting lines between them. A set of blocks convenient for this purpose is defined in Figure 3.7.

All blocks except the terminal block, which has no exit, and logical decision blocks, which have two or more exits, may have any number of entry paths but only one exit path. A test for a logical decision is usually framed as a question to which the answer is 'Yes' or 'No', each exit from the Lozenge block being marked by the appropriate answer.

A block diagram showing the selection process is shown in Figure 3.8. The most important parts of this process are:

- The weighing of the hydraulic properties of the structure against the actual situation or environment in which the structure should function (boundary conditions);
- The period of reflection, being the period during which the engineer tests the type of structure and decides whether it is acceptable.

Both parts of the selection process should preferably be passed through several times to obtain a better understanding of the problem.

To assist the engineer to find the most appropriate type of structure, and thus the

TABLE 3.1. DATA ON VARIOUS STRUCTURES

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
Name of structure and section number in which structure is described	Sketch of structure	Shape of control section perpendicular to flow and u-value	M = measuring MR = measuring & regulating	H <sub>1</sub> min or Δh min	H <sub>1</sub> max or Δh max	minimum crest height above approach channel bottom p	minimum size of control b or B, w and D <sub>p</sub>	range of notch angle θ degrees	Q <sub>min</sub>  m <sup>3</sup> /s	Q <sub>max</sub> in m <sup>3</sup> /s or q max in m <sup>3</sup> /s	Y = Q <sub>max</sub> / Q <sub>min</sub>	modular limit H <sub>2</sub> /H <sub>1</sub> or head loss	error in C <sub>d</sub> C <sub>v</sub> or C <sub>e</sub> (%)	sensitive- ness at minimum head % per 0.01 m	debris passing capacity + + very good; + good; □ fair; - poor; - - very poor	sediment passing capacity	Remarks
Round-nose horizontal broad-crested weir (4.1)		rectangular u = 1.5	MR	0.06 m 0.05 L	0.5 L	0.15 m 0.33 H <sub>1</sub>	0.30 m H <sub>1</sub> max 0.2 L	-	0.0066 b = 0.30 m	q = 4.7 H <sub>1</sub> = 2.0 m	35	0.70 to* 0.95	2(21-20 C <sub>d</sub> )	25	+	□	* value depends on slope backface and on ratio p <sub>2</sub> /H <sub>2</sub>
Romijn movable measuring/regulating weir (4.2)		rectangular u = 1.5	MR	0.05 m 0.12 L	0.78 L	0.15 m 0.33 H <sub>1</sub>	0.30 m H <sub>1</sub> max	-	0.0057* b = 0.30 m	Q = 0.860* b = 1.50 m	30	0.30	3	30	+	+	* values refer to standard weir with L = 0.60 m
Triangular broad-crested weir (4.3)		(truncated) triangular u = 1.7 to 2.5	MR	0.06 m 0.05 L	0.5 L to 0.7 L	0.15 m 0.33 H <sub>1</sub>	0.30 m H <sub>1</sub> max 0.2 L	30 to 180	0.0026 at θ = 30°	variable	830*	0.80 to 0.95	2(21-20 C <sub>d</sub> )	42	+ to □ depending on θ	□	* triangular control 0.05 L ≤ H <sub>1</sub> ≤ 0.7 L
Broad-crested rectangular profile weir (4.4)		rectangular u = 1.5	MR	0.06 m 0.08 L	0.85 L* 1.50 L →	0.15 m if 0.4 h <sub>1</sub> if 0.65 h <sub>1</sub>	0.30 m h <sub>1</sub> max 0.2 L	-	0.0064	q = 5.07 H <sub>1</sub> = 2.0 m	35* 81	0.66 to 0.38	10F-8 1 ≤ F ≤ 1.24	25	□	□	* depending on weir height p
Faiyum weir (4.5)		rectangular u = 1.6	M	0.06 m 0.08 L	1.6 L	0.15 m	0.05 m 3h <sub>1</sub> /A <sub>1</sub>	-	0.0011	q = 5.1 H <sub>1</sub> = 2.0 m	90	0.66*	5	25	□	-	* usually lower
Rectangular sharp-crested weirs (5.1)		rectangular u = 1.5	M → MR →	0.07 m	0.60 m 0.5 b	0.30 m 2 h <sub>1</sub>	0.30 m B - b > 4 h <sub>1</sub>	-	0.00997	q = 0.813	24.5 if b > 1.2 m	head loss = H <sub>1</sub> + 0.05 m	1	25	- -	- -	Fully contracted weir
V-notch sharp-crested weirs (5.2)		triangular u = 2.5	M	0.05 m	0.60 m 1.2 p	0.10 m	B <sub>1</sub> ≥ 2.5 h <sub>1</sub>	90	0.00137	variable	about 30	head loss = H <sub>1</sub> + 0.05 m	1	25	-	- -	Full width & partially contracted weirs
Cipoletti weir (5.3)		trapezoidal u = 1.5	MR	0.06 m	0.60 m	0.30 m 2 h <sub>1</sub>	b ≥ 0.30 m 0.5 h <sub>1</sub>	-	0.0008	Q = 0.390 about	about 500	head loss ≥ H <sub>1</sub>	2	50	- -	- -	partially contracted
Circular weir (5.4)		circular u is variable but ≤ 2.0	M	0.05 m	0.38 m 0.4 p	0.45 m	B <sub>1</sub> ≥ 5.0 h <sub>1</sub>	25 to 100	0.0002 if θ = 28° 4'	Q = 0.145 if θ = 100°	about 150	head loss ≥ H <sub>1</sub>	1	50	- -	- -	fully contracted
Proportional weir (5.5)		proportional u = 1.0	M	0.03 m 2 a	such that x ≤ 0.005 m	p = 0 or p ≥ 0.15 m	0.15 m	-	Q = 0.0082 b = 0.30 m	q = 0.864	36.4	head loss H <sub>1</sub> + 0.05 m	5	25	- -	- -	
Weir sill with rectangular control section (6.1)		rectangular u = 1.5	M	0.03 m 0.1 d	0.9 d	0.10 m 0.5 d	d ≥ 0.20 m	-	0.00091 d = 0.20 m	variable	55.9 if d ≥ 0.30 m	head loss H <sub>1</sub> + 0.05 m	2	67	- -	- -	
V-notch weir sill (6.2)		triangular u = 2.5	M	0.0058 a = 0.006 m b = 0.15 m	variable	small, but depends on a-value	head loss H <sub>1</sub> + 0.05 m	2	33	- -	- -	good if p = 0	a ≥ 0.005 m				
Triangular profile two-dimensional weir (6.3)		rectangular u = 1.5	M	0.09 m 0.75 L	0.90 m 0.5 b	0	0.30 m b ≥ 1.25 b <sub>1</sub>	-	0.013 b = 0.30 m	q = 1.366	32	0.20	5	17	+	+	
									0.0005 0.0007 0.0010	Q = 25.4** Q = 30.6 Q = 49.4	50000* 43000 49000	0.30	3	83	□	-	*three notch angles only **depending on A <sub>1</sub> -values
									0.0031 h <sub>1</sub> = 0.03 m 0.0088 b = 0.30 m h <sub>1</sub> = 0.06 m	q = 10.18	1000* or 350	0.75	10 C <sub>v</sub> - 9	50 or 25	++	+	* depends on crest material. Applies to 1-to-5 back face

TABLE 3.1. DATA ON VARIOUS STRUCTURES (cont.)

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	
Name of structure and section number in which structure is described	Sketch of structure	Shape of control section perpendicular to flow and u-value	M = measuring MR = measuring & regulating	H <sub>1</sub> min or Δh min	H <sub>1</sub> max or Δh max	minimum crest height above approach channel bottom p	minimum size of control b or B, w and D <sub>p</sub>	range of notch angle θ degrees	Q <sub>min</sub> m <sup>3</sup> /s	Q <sub>max</sub> in m <sup>3</sup> /s or q max in m <sup>2</sup> /s	γ = $\frac{Q_{max}}{Q_{min}}$	modular limit H <sub>2</sub> /H <sub>1</sub> or head loss	error in C <sub>d</sub> C <sub>v</sub> or C <sub>e</sub> (%)	sensitive-ness at minimum head % per 0.01 m	debris passing capacity ++ very good; + good; □ fair; - poor; -- very poor	sediment passing capacity + good; - very poor	Remarks	
Triangular profile flat-vee weir (6.4)		(truncated) triangular u = 1.7 to 2.5	M	0.03 m steel 0.06 m concrete	3.00 m 3.0 p	0.06 m 0.33 H <sub>1</sub>	0.30 m 2 H <sub>1</sub>	168°34' 174°16'	0.0137 h=0.03 m 0.0275 h <sub>1</sub> =0.06 m b=0.30 m	depends on degree of truncation	100,000* h <sub>1</sub> ≥ 0.03 m 17,500 h <sub>1</sub> ≥ 0.06 m	0.67	10 C <sub>v</sub> -8	83 if h <sub>1</sub> =0.03 m 42 if h <sub>1</sub> =0.06 m	++	+	Applies to 1-to-5 back face only. *γ-values decrease if control is more truncated	
Butcher's movable standing wave weir (6.5)		rectangular u = 1.6	MR	0.05 m	1.00 m	1.4 h <sub>1</sub> max	0.30 m 2 h <sub>1</sub>	-	0.0077 b=0.30 m	q=2.30	120	0.70	3	32	+	-*	* good if gate arrangement as in Section 4.2	
WES-Standard spillway (6.6)		rectangular u = 1.5	M	0.06 m	depends* on h <sub>d</sub> 5.0 p	0.15 m 0.2 h <sub>1</sub>	0.30 m 2 H <sub>1</sub>	-	0.025 b=1.0 m	variable*	about 1000 but depends on h <sub>d</sub> -value	0.30	5	25	++	+	* minimum pressure on crest limited to -4.0 m water column (see Fig.6.17)	
Cylindrical crested weir (6.7)		rectangular u = 1.5	MR	0.06 m 0.1 r	depends* on r 3.0 p	0.15 m 0.33 h <sub>1</sub>	0.30 m 2 H <sub>1</sub>	-	0.0064 b=0.30 m	variable*	about 750, but depends on ratio H <sub>1</sub> /r	0.33	5	25	++	+	* minimum pressure on crest limited to -4.0 m water column (see Fig.6.23)	
Long-throated flumes (5 basic shapes) (7.1)		rectangular u = 1.5	M	0.06 m 0.1 L	1.0 L 1.0 B	0 but Fr ≤ 0.5	0.30 m*	-	0.0066 b=0.30 m	variable with throat length	35	0.70 to 0.95 depending on downstream transition	2(21-20C <sub>d</sub> ) for all flumes	25	++	+	* for all flumes; at maximum stage: B > 0.30 m B > H <sub>1</sub> max B > L/5	
		(truncated) triangular u=1.7 to 2.5	M			for all flumes	B ≥ 0.10 m*	30 to 180	0.00098 θ=90°	≤ 315				28 to 42	++	++		
		trapezoidal u=1.6 to 2.4	M			for all flumes	B ≥ 0.30 m*	side slope variable**	0.0036 b=0.08 m slope 1:2	≤ 250				27 to 40	++	++	**side slope ratio horz : vert. varies between 1:1 to 4:1	
		parabolic u = 2.0	M			Note: in general H <sub>1</sub> ≤ 3.0 m	f ≥ 0.10 m*	-	0.0027 f=0.10 m	100				33	++	++		
Throatless flumes with rounded transition (7.2)		(semi)-circular u is variable but ≤ 2.0	M				d ≥ 0.20 m*	-	0.0026 d=0.20 m		100 if d ≥ 0.60 m			≤ 33	++	++		
		rectangular u = 1.5	M	0.06 m	2.00 m 1.5 R	0	0.20 m H <sub>1</sub> max	-	0.0050 b=0.20 m	q=4.82 H <sub>1</sub> =2.00 m	190	about* 0.50	8	25	++	+	* if radii of rounding and if downstream transition comply with Section 7.2.2	
		rectangular u = 1.5	M	0.06 m	1.80 m	0	0.305 m only	-	-	-	-	-	-	25	++	+	not recommended to be constructed due to lack of data	
Parshall flumes (22 types) (7.4)		rectangular u = 1.55	M	0.015 m and 0.03 m	0.21 m to 0.33 m	0 level floor	0.0254 m to 0.0762 m	-	0.00009 to 0.00077	0.0054 to 0.0321	about 55	0.50	3	103 to 52	++	+	very small flumes; 1, 2, and 3 inch wide	
		u = 1.522 to u = 1.607	M	0.03 m, 0.045 m, and 0.076 m	0.45 m to 0.76 m		0.1524 m to 2.438 m	-	0.0015 to 0.0972	0.111 to 3,949	about 75	0.60 and 0.70	3	53 to 21	++	+	small flumes; 0.5, 0.75, 1.0, 1.5, 2, 3 to 8 feet wide	
		u = 1.60	M	0.09 m	1.07 m to 1.83 m		3.048 m to 15.24 m	-	0.16 to 0.75 m <sup>3</sup> /s	8.28 to 93.04 m <sup>3</sup> /s	about 105	0.80	3	18	++	+	large flumes; 10 to 50 feet wide	
H-flumes (3 types) (7.5)		sloping trapezium u = 2.0 to 2.4	M	0.01 m to 0.04 m	0.11 m to 0.30 m	0	see Figure 7.21	-	0.000012 to 0.00034	0.0003 to 0.0223	about 100	0.25	3	≤ 240	-	-	HS-flumes, D=0.4, 0.6, 0.8 and 1.0 ft	
			M	0.01 m to 0.03 m	0.14 m to 1.36 m			-	0.000031 to 0.0014	0.009 to 2.336	about 750	0.25	3	≤ 240			H-flumes, D=0.5, 0.75, 1.0, 1.5, 2.0, 2.5, 3.0, and 4.5 ft	
			M	0.03 m	1.06 m and 1.21 m				-	0.0018 and 0.0020	2.369 and 3.326	about 1500	0.25	3	≤ 80	+		HL-flumes, D=3.5 and 4.0 ft
			M						-									
Circular sharp-edged orifice (8.1)		circular u = 0.5	M	Δh ≥ 0.03 m h <sub>1</sub> ≥ d	-	0.5 d	A ≤ 10 A <sub>1</sub> d ≥ 0.02 m	-	0.00014 d=0.02 m	variable	5.8*	submerged	1	17	--	--	* 0.03 m ≤ Δh ≤ 1.0 m	
Rectangular sharp-edged orifice (8.2)		rectangular u = 0.5	M but MR if suppressed	Δh ≥ 0.03 m y <sub>1</sub> ≥ 0.15 m	-	0	b ≥ 0.30 m w ≥ 0.02 m	-	0.0028	variable	5.8*	submerged	2 to 3	17	--	□ if p=0	* 0.03 m ≤ Δh ≤ 1.0 m and A = constant	
Constant head orifice (8.3)		rectangular u = 0.5	MR	Δh = 0.06 m y <sub>1</sub> ≥ 2.5 w	Δh = 0.06 m	0	usually* b = 0.60 m and b = 0.75 m	-	0.0086* 0.0107	Q = 0.140* Q = 0.280	16** 26	submerged, but usually ΔH <sub>L</sub> ≥ 0.30 m	≥ 7	8	--	-	* Two sizes of orifice gates, 0.60x0.45 m & 0.75x0.60 m are com. used ** If A varies	

TABLE 3.1. DATA ON VARIOUS STRUCTURES (cont.)

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
Name of structure and section number in which structure is described	Sketch of structure	Shape of control section perpendicular to flow and u-value	M = measuring MR = measuring & regulating	H <sub>1</sub> min or Δh min	H <sub>1</sub> max or Δh max	minimum crest height above approach channel bottom p	minimum size of control b or B, w and D <sub>p</sub>	range of notch angle degrees	Q <sub>min</sub> m <sup>3</sup> /s	Q <sub>max</sub> in m <sup>3</sup> /s or q max in m <sup>2</sup> /s	γ = $\frac{Q_{max}}{Q_{min}}$	modular limit H <sub>2</sub> /H <sub>1</sub> or head loss	error in C <sub>d</sub> C <sub>v</sub> or C <sub>e</sub> (%)	sensitive-ness at minimum head % per 0.01 m	debris passing capacity + + very good; + good; □ fair; - poor; - - very poor	sediment passing capacity + + very good; + good; □ fair; - - very poor	Remarks
Radial or Tainter gate (8.4)		rectangular u = 0.5	MR	y <sub>1</sub> ≥ 0.15 m y <sub>1</sub> ≥ 1.25 w y <sub>1</sub> ≥ 0.1 r	y <sub>1</sub> < 1.2 r	0	b ≥ 0.30 m w ≥ 0.02 m	-	0.005 y <sub>1</sub> = 0.15 m	variable	about* 35	variable	5	8	-	+	* If A varies γ is greater if gate is lifted entirely
Crump-de Gruyter adjustable orifice (8.5)		rectangular u = 0.5	MR	0.03 m 1.58 w	0.60 m	0.20 m p = b	b ≥ 0.20 m 0.02 m ≤ w ≤ 0.38 m w ≤ 0.63 h <sub>1</sub>	-	0.0088	q = 0.742	10	up to* 0.25	3	8	-	-	* If w/h <sub>1</sub> is small
Meter gate (8.6)		Section of circle u = 0.5	MR	h <sub>1</sub> ≥ 1.0 D <sub>p</sub> Δh ≥ 0.05 m	Δh ≤ 0.45 m	0.17 D <sub>p</sub>	D <sub>p</sub> ≥ 0.30 m w ≤ 0.75 D <sub>p</sub> w ≥ 0.02 m	-	0.0076 D <sub>p</sub> = 0.30 m	Q = 2.10 D <sub>p</sub> = 1.22 m	7 to 45	h <sub>2</sub> ≥ 0.15 m ΔH <sub>L</sub> ≥ 0.30 m	3 to 6	8	-	-	Usually 0.20 m ≤ D <sub>p</sub> ≤ 1.22 m
Neyric modules (8.7)		rectangular u = 0.5	MR	h <sub>d</sub> = 0.17 m h <sub>d</sub> = 0.28 m	h <sub>d</sub> ≤ P and h <sub>d</sub> ≤ 0.35 P <sub>2</sub>	0.16 m 0.26 m	0.05 m 0.05 m	-	0.0005 0.0010	q = 0.100 q = 0.200	1* 1	0.60 0.60	5 5	3 1.8	- -	□ □	Type X 1 Type XX 2 * Discharge is regulated by opening/closing gates
Danaidean tub (8.8)		circular or rectangular u = 0.5	M	approx. 0.10 m	approx. 5.0 m	-	d ≥ 0.02 m b ≥ 0.02 m	0° ≤ B ≤ 180°	0.00027 d = 0.02 m h <sub>1</sub> = 0.10 m	variable	7	h <sub>1</sub> + δd*	2	5	- -	□	* δ = contraction coefficient
Divisors (9.1)		rectangular u = 1.5	MR	0.06 m 0.50 r	1.0 p 0.35 P <sub>2</sub> 4.0 r	0.15 m 0.33 H <sub>1</sub>	0.30 m 2.0 H <sub>1</sub>	-	0.0075 b = 0.30 m	q = 5.69 H <sub>1</sub> = 2.00 m	30*	0.60	5	25	- -	+	* Other weir profiles are possible
Pipes and small siphons (9.2)		circular u = 0.5	M	0.03 m	1.20 m	1.0 D <sub>p</sub>	D <sub>p</sub> ≥ 0.015 m D <sub>p</sub> ≥ 0.03 m	-	0.00006 0.00037	variable	6 6	usually submerged	10 10	17 17	- -	- -	L > 20 D <sub>p</sub> 6 D <sub>p</sub> ≤ L ≤ 20 D <sub>p</sub>
Fountain flow from vertical pipe (9.3)		circular u = 1.35 or u = 0.53	M	0.03 m	4.00 m	-	0.025 ≤ D <sub>p</sub> D <sub>p</sub> ≤ 0.609	-	0.00048 D <sub>p</sub> = 0.025 m	Q = 2.45 D <sub>p</sub> = 0.609 m	237	pipe must discharge free into the air	15 to 20	50	- -	- -	
Flow from horizontal pipes (9.4)		circular 1.5 < u ≤ 2 u = 1.5 (versus Y)	M	y <sub>e</sub> = 0.02 m 0.1 D <sub>p</sub>	y <sub>e</sub> ≤ 0.56 D <sub>p</sub>	-	D <sub>p</sub> ≥ 0.05 m	-	0.00062 D <sub>p</sub> = 0.05 m	variable	42	pipe must discharge free into the air	3	100	- -	- -	Brink depth method
Brink depth method for rectangular canals (9.5)		rectangular u = 1.5	M	y <sub>e</sub> ≥ 0.03 m	-*	p = 0	0.30 m 3 y <sub>c</sub>	-	0.0020 D <sub>p</sub> = 0.05 m	Q = 0.100 D <sub>p</sub> = 0.15 m	2.5	free into the air	15	20	- -	- -	Trajectory method; X = 0.152, 0.305 and 0.457 m
Dethridge meters (9.6)		rectangular no u-value	MRV	y <sub>1</sub> = 0.30 m y <sub>1</sub> = 0.38 m	y <sub>1</sub> = 0.90 m y <sub>1</sub> = 0.90 m	-	0.52 m 0.78 m	-	0.0081 b = 0.30 m	q = 4.82 H <sub>1</sub> = 2.0 m	about 175	head loss 2.1 H <sub>1</sub>	3	25	+	+	y <sub>e</sub> /y <sub>c</sub> = 0.715 * Approach canal length ≥ 12 y <sub>c</sub>
Propeller meters (9.7)		usually circular no u-value	MRV	v > 0.45 m/s	v < 5.0 m/s	-	0.05 m ≤ D <sub>p</sub> ≤ 1.82 m	-	0.015 0.040	Q = 0.070 Q = 0.140	4.6 3.5	head loss ≥ 0.08 m ≥ 0.09 m at y <sub>1</sub> min.	5 5	-	+	+	Small meter Large meter
									0.00088 D <sub>p</sub> = 0.05 m	Q = 13.0 D <sub>p</sub> = 1.82 m	10	usually Δh ≥ 0.50 m	5*	-	□	+	* If propeller is maintained frequently