Purpose
The purpose of this guide is to assist dam owners and operators in understanding the need for vehicle barriers as part of an overall security plan and familiarize security personnel with the various types of active and passive vehicle barriers. This guide also provides a very cursory level of technical information regarding barriers and includes references to assist owners and operators in properly designing and selecting vehicle barriers and their appurtenant safety and security systems.

Security Plan
Most dams should have a site-specific security plan. Among other information, this plan should identify the likely threats at that site and the measures taken to counteract them. The need for vehicle access control to protect against the possible use of vehicle-borne improvised explosive devices (VBIEDs) may be necessary and, if required, should be addressed in the site security plan.

Most VBIEDs are stationary; the vehicle is parked in close proximity to an asset and is remotely detonated when a target passes by or when people have gathered in the area. This type of VBIED use is generally limited to areas with unrestricted access; it is not the focus of this brochure.

A more sophisticated type of attack is when an aggressor uses a moving VBIED to penetrate a controlled perimeter and immediately detonate the explosives at or near a high-value target. For this type of threat, it is critical to have a comprehensive vehicle control plan for the site. This brochure addresses the types of barriers that could be considered in an access control plan for moving VBIEDs.

Access Control Plan
The threat and vulnerability assessments that form the basis for the site security plan and vehicle access control plan should contain or outline a description of the threat vehicle types, sizes, and weights that need to be protected against. The overall access control plan should address appropriate vehicular and personnel (if applicable) access to the site, not only to check or validate credentials, as needed, but to check vehicle contents as well. A general access control plan may include an access control point (ACP) with signage, fencing, gates, barriers (both active and passive), and structures such as a guard booth, search area, or visitor control center.

Development of the vehicle access control plan depends on several factors. First, the acceptable standoff distance must be determined. This determination depends on the likely magnitude (type and size) of the explosive and the asset’s susceptibility to compromise and/or damage from it. The second factor is the type of vehicle used. Passenger cars can carry far less explosives than semi-trailers; other types of delivery trucks would fall somewhere between these extremes. Finally, an analysis must be done to determine how fast the vehicle will be moving when it strikes a barrier.

A simple, spreadsheet-based analysis tool which accounts for parameters such as vehicle acceleration, approach slope, approach distance, approach width, minimum/maximum turn radius, super elevation, etc. for calculating the maximum vehicle velocity and vehicle kinetic energy is available on the Homeland Security Information Network-Critical Sectors (HSIN-CS) Dams Portal. A copy of the spreadsheet is depicted in Attachment 1; Attachment 3 contains the formula for calculating kinetic energy.

It is typically less costly to design barriers for a slow-moving sedan than a fast-moving flatbed truck. It might be possible to limit vehicle speeds by configuring speed management features both inside and outside the perimeter or by placing various traffic control devices in the corridor to force vehicles to maneuver slowly. The key design criteria are determining and effectively mitigating the threat vehicle’s mass (weight) and its speed.

The access control plan should also take into account the surrounding terrain and the critical components that need protection. Areas that are not accessible by vehicle do not require barriers. Rough terrain can reduce vehicle speeds and allow for the use of less costly barriers. The access control plan should contain features that guard against the possibility of vehicles running off road and ramming next to the entrance.

The notional site in Attachment 2 shows areas that require barriers with the type of barrier dependent on the terrain and design threat. It further demonstrates that there must
be a continuous ring of active and passive vehicle barriers around the area to be protected. Figure 1 also illustrates the use of active and passive barriers to restrict access.

In recent years, it has become common to see more sophisticated barrier systems or systems designed to limit the penetration of a moving vehicle that might attempt to drive through a gate or gain vehicular access to an asset. For example, the U.S. Department of State (DOS) often specifies barriers for its facilities that limit the penetration to 1 meter or less for a 15,000-pound truck traveling at 30, 40, or 50 miles per hour. Because of their much higher costs, these types of barriers should be used only where a risk assessment has identified a set of higher threats and/or consequences that would justify the added expense. Where consequences are significant, and the location remote, it may be prudent to install a barrier with a rating higher than called for by the analysis because the heavier, more robust barrier may provide greater resistance to tamper and defeat at a modest increase in cost.

Passive Vehicle Barriers
Where protection is necessary against stationary or moving VBIEDs, the site or asset controlled perimeter could be established with a passive vehicle barrier system. Passive barriers have no moving parts; their effectiveness relies on their ability to absorb energy and transmit it to their foundations. They may be movable or permanent and can be of many types, as discussed below.

Fences can be used as barriers, but normal fences are not effective in stopping moving vehicles. Chain-link fences can be supplemented with high-strength cables, mounted with the fence and securely anchored, as shown in Figure 2. This is similar to the double, triple, or quadruple cable systems often used in the medians and shoulders of some highways to prevent cross-over accidents.
Active Vehicle Barriers

Vehicle access control points or entry control points where credentials and/or vehicle contents are checked might require installation of an active vehicle barrier (AVB) at the end of the access corridor. The appropriate type of barrier depends on a number of factors, as listed below.

- If the entry is unstaffed all or part of the time, is there a need for a moveable gate that can act as a pedestrian barrier when closed?
- When entry is unstaffed will the barrier resist/prevent unauthorized operation or tampering?
- When the entry is unstaffed, what can be done to provide supervision or monitoring of the barrier (tamper and/or intrusion sensors, video assessment)?
- When the entry is staffed, will the barrier normally be open or closed? If the barrier is normally open, is there a need for a back-up barrier that can be closed quickly if a vehicle attempts to force its way past the entry control point?
- What is the design speed and weight of the vehicle that must be stopped?
- How quickly must the barrier open or close?

- What environmental conditions might affect operation?
- Is it permissible to place the barrier foundations in the engineered fill of an embankment dam?
- What are the maintenance requirements?
- What impact will the proposed barrier have on motorist safety?
- What impact will the operation of an active barrier have on public and guard-staff safety?
- Are aesthetics important at this location?
- For a remote location, what is the expected law enforcement response time?

Further discussion of these factors is available in Military Handbooks 1013/10 and 1013/14 (see references 1 and 2).

Gates, traffic arms/-beams, bollards, plates, and nets are among the most commonly used AVBs. Each is described below.

The term “gate,” when used for vehicle control, is often used to refer to a moveable portion of fencing, as illustrated in Figure 1. The gate usually matches the adjacent fixed fencing, but is mounted on wheels or hinges so that it can be opened and closed manually or with a gate operator to accommodate remote operation. These types of barriers typically complete the outer controlled pedestrian access perimeter. However, most fence-type gates are not designed to stop a moving vehicle that attempts unauthorized entry.

Traffic arm barriers are common at many paid parking facilities and toll booths. However, these devices have no stopping power. There are similar AVBs that are designed and able to resist a moving vehicle impact. These AVBs use a much stronger or reinforced arm which is typically anchored into massive supports on both sides of the roadway.

Retractable bollards are another common type of AVB. They are frequently used where they are normally in an up position and only need to be operated infrequently.

A wedge barrier gets its name from the distinctive wedge shape, when viewed from the side. Another common name for this barrier is plate barrier because, when activated, the barrier consists of a steel plate angled upward toward the approaching vehicle. When not activated, the plate is flush with the roadway enabling motorists to pass. These barriers can be very effective in resisting high-speed impacts. They can also be designed to deploy very quickly (e.g., within 1 second) during an emergency fast operate (EFO) activation.

Barrier-net systems include energy absorbers and are attached to vertical steel end supports that are anchored in concrete. Some net systems can span more than 200 feet without requiring fixed, intermediate supports but have the capability to stop a 15,000-pound vehicle at impact speeds.
of over 50 mph. Barrier-net systems can be easily installed and placed in series to provide extensive perimeter coverage.

Safety
All these AVBs can create a temporary obstruction across a roadway, which obviously has the potential to cause safety problems. Unintended AVB activation can cause injury or death to motorists. Accordingly, appropriate speed limits need to be enforced and implementation of safety features such as warning signs, additional signals, and detection loops in the access corridor are essential for any AVB installation. Safety is of particular concern where rapid deployment is possible, such as with wedge barriers. Safety issues are addressed in reference 3.

Environment and Operations
Active barriers must be capable of operating continuously. Their materials, hydraulics, hinges, movable parts, and electrical connections must be capable of operating in the site’s specific environmental conditions. In addition to being operational in freezing rain, high heat, and heavy wind, snow, rain, or dust, the systems must have reasonable installation and maintenance costs. Part of the active barrier selection process is full awareness of what the manufacturer requires in terms of installation, operations, and maintenance schedules and procedures to ensure maximum system reliability.

More detailed selection and procurement recommendations are available in the Department of Defense (DoD) guide specification for active vehicle barriers, Unified Facilities Guide Specifications (UFGS) 34 71 13.19 (see reference 5). Note that this guide and the guides listed below as technical resources are intended to be applicable under all situations; their recommendations must therefore be tailored to the specific types of barriers required, site design constraints, and environmental factors.

Barrier Selection and Specification
Selection of appropriate passive or active vehicle barriers must begin with consideration of the many factors discussed above. For high-risk situations, stopping power—limiting penetration of a threat vehicle—can be the primary requirement. The DOS, DoD, and ASTM International have extensive experience with vehicle barriers and established standardized test procedures to evaluate the level of performance of these systems.

Beyond numerical analysis of a barriers performance it is important to consider factors unique to the dam such as remote location, unstaffed and unsupervised locations, and law enforcement response time, which allow significant opportunity and time for an attacker to defeat, tamper with, dismantle, destroy or circumvent a vehicle barrier system. To address these unique risks and vulnerabilities, mitigation methods such as monitoring, robustness, redundancy, tamper resistance, and anti-ramping measures should be considered.

The DOS testing and AVB certification standard was based on the kinetic energy (K) of a 15,000-pound vehicle traveling at 30, 40 or 50 mph, where the dynamic penetration of the vehicle is limited to 1 meter or less. Since DOS installations generally have little standoff distance between the asset(s) and the perimeter, DOS determined that 1-meter maximum dynamic penetration is the difference between a passing and failing test.

The barrier designations/DOS certification ratings are shown in Table 1. Effective February 1, 2009, however, the DOS will no longer be certifying anti-ram barriers under its testing procedure; it will only evaluate barriers under the ASTM F 2656-07 Standard Test Method for Vehicle Crash Testing of Perimeter Barriers.

Table 1: Department of State AVB Certification Ratings

<table>
<thead>
<tr>
<th>Rating</th>
<th>Vehicle Weight</th>
<th>Vehicle Speed</th>
</tr>
</thead>
<tbody>
<tr>
<td>K4</td>
<td>15,000 lb</td>
<td>30 mph</td>
</tr>
<tr>
<td>K8</td>
<td>15,000 lb</td>
<td>40 mph</td>
</tr>
<tr>
<td>K12</td>
<td>15,000 lb</td>
<td>50 mph</td>
</tr>
</tbody>
</table>

The ASTM test standard provides the basis for certifying barriers for several vehicle sizes (small passenger car (C), pick-up truck (P), medium-duty truck (M), and heavy goods vehicle (H)) and different vehicle speeds (30, 40, 50, and 60 mph) and defines penetration categories which may be acceptable in certain applications. These ratings are depicted in Table 2. A M30 P1 rating means that a medium-duty truck weighing 15,000 pounds and traveling at 30-mph would not achieve a dynamic penetration of more than 1 meter.

Table 2: ASTM Penetration Ratings

<table>
<thead>
<tr>
<th>Designation</th>
<th>Dynamic Penetration Rating</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1</td>
<td>≤1 meter (3.3 feet)</td>
</tr>
<tr>
<td>P2</td>
<td>1.01 to 7 meters (3.31 to 23.0 feet)</td>
</tr>
<tr>
<td>P3</td>
<td>7.01 to 30 meters (23.1 to 98.4 feet)</td>
</tr>
<tr>
<td>P4</td>
<td>30 meters (98 feet) or greater</td>
</tr>
</tbody>
</table>

For its sites, the DOS will only consider barriers with an ASTM F 2656-07 rating of M30 P1, M40 P1, and M50 P1.
6. Department of Defense, UFC 4-022-02, Security Engineering: Design and Selection of Vehicle Barriers

## Attachment 1: Vehicle Barrier Selection

### Table A1-1: Vehicle Parameters

<table>
<thead>
<tr>
<th>Vehicle Parameters</th>
<th>W (lb)</th>
<th>Mass (slug)</th>
<th>Acceleration Rate (ft/sec/sec)</th>
<th>Coefficient of Friction</th>
</tr>
</thead>
<tbody>
<tr>
<td>Truck</td>
<td>15,000</td>
<td>466</td>
<td>6.0</td>
<td>1</td>
</tr>
<tr>
<td>Car</td>
<td>4,000</td>
<td>124</td>
<td>11.3</td>
<td>1</td>
</tr>
</tbody>
</table>

### Table A1-2: Maximum Speed to Curve (or Barrier) for a Given Distance, Grade, and Acceleration

\[
V = \sqrt{V_0^2 + 2ad}
\]

<table>
<thead>
<tr>
<th>Input Beginning Speed (mph)</th>
<th>25</th>
<th>Input Distance (ft)</th>
<th>234</th>
<th>Input Slope + or - (deg)</th>
<th>-5</th>
<th>Acceleration Gravity (ft/sec/sec)</th>
<th>2.8</th>
<th>Truck Acceleration (ft/sec/sec)</th>
<th>6</th>
<th>Car Acceleration (ft/sec/sec)</th>
<th>11</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input Beginning Speed (mph)</td>
<td>25</td>
<td>Input Distance (ft)</td>
<td>234</td>
<td>Input Slope + or - (deg)</td>
<td>-5</td>
<td>Acceleration Gravity (ft/sec/sec)</td>
<td>2.8</td>
<td>Truck Acceleration (ft/sec/sec)</td>
<td>6</td>
<td>Car Acceleration (ft/sec/sec)</td>
<td>11</td>
</tr>
<tr>
<td>Truck Acceleration (ft/sec/sec)</td>
<td>6</td>
<td>74</td>
<td>81</td>
<td>50.4</td>
<td>1,274,288</td>
<td>Car Acceleration (ft/sec/sec)</td>
<td>11</td>
<td>89</td>
<td>98</td>
<td>60.8</td>
<td>494,016</td>
</tr>
</tbody>
</table>

### Table A1-3: Maximum Speed through a Curve for a Given Turning Radius and Road Pitch

\[
V = \sqrt{V_0^2 + 2ad}
\]

<table>
<thead>
<tr>
<th>Input Radius (ft)</th>
<th>107</th>
<th>Input Road Pitch + or - (deg)*</th>
<th>0</th>
<th>Coefficient of Friction</th>
<th>1.0</th>
<th>Truck</th>
<th>59</th>
<th>64</th>
<th>40.0</th>
<th>803,248</th>
<th>K12</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input Radius (ft)</td>
<td>107</td>
<td>Input Road Pitch + or - (deg)*</td>
<td>0</td>
<td>Coefficient of Friction</td>
<td>1.0</td>
<td>Truck</td>
<td>59</td>
<td>64</td>
<td>40.0</td>
<td>803,248</td>
<td>K12</td>
</tr>
</tbody>
</table>

### Table A1-4: Maximum Speed Between Curve and Barrier with Given Grade, Acceleration and Distance Between Curve and Barrier

<table>
<thead>
<tr>
<th>Beginning Speed (mph)</th>
<th>40.0</th>
<th>Input Distance (ft)</th>
<th>56</th>
<th>Input Slope + or - (deg)</th>
<th>0</th>
<th>Gravity (ft/sec/sec)</th>
<th>0.0</th>
<th>Truck Acceleration (ft/sec/sec)</th>
<th>6</th>
<th>Car Acceleration (ft/sec/sec)</th>
<th>11</th>
</tr>
</thead>
<tbody>
<tr>
<td>Beginning Speed (mph)</td>
<td>40.0</td>
<td>Input Distance (ft)</td>
<td>56</td>
<td>Input Slope + or - (deg)</td>
<td>0</td>
<td>Gravity (ft/sec/sec)</td>
<td>0.0</td>
<td>Truck Acceleration (ft/sec/sec)</td>
<td>6</td>
<td>Car Acceleration (ft/sec/sec)</td>
<td>11</td>
</tr>
<tr>
<td>Truck Acceleration (ft/sec/sec)</td>
<td>6</td>
<td>48</td>
<td>52</td>
<td>32.5</td>
<td>530,079</td>
<td>Car Acceleration (ft/sec/sec)</td>
<td>11</td>
<td>54</td>
<td>59</td>
<td>36.5</td>
<td>178,258</td>
</tr>
</tbody>
</table>

Note: Beginning Speed taken from “Speed Through Curve” table above.

### Table A1-5: For Barriers Parallel to Road

<table>
<thead>
<tr>
<th>Input Road Width (ft)</th>
<th>80</th>
<th>Input Speed of Vehicle (mph)</th>
<th>40.0</th>
<th>Min Radius</th>
<th>107</th>
<th>Attack Angle (deg)</th>
<th>75.4</th>
<th>Factored Speed (mph)</th>
<th>38.7</th>
<th>Factored Energy (ft lb)</th>
<th>751,629</th>
<th>Required Barrier Speed Rating</th>
<th>K8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input Road Width (ft)</td>
<td>80</td>
<td>Input Speed of Vehicle (mph)</td>
<td>40.0</td>
<td>Min Radius</td>
<td>107</td>
<td>Attack Angle (deg)</td>
<td>75.4</td>
<td>Factored Speed (mph)</td>
<td>38.7</td>
<td>Factored Energy (ft lb)</td>
<td>751,629</td>
<td>Required Barrier Speed Rating</td>
<td>K8</td>
</tr>
<tr>
<td>Truck</td>
<td>40.0</td>
<td>107</td>
<td>75.4</td>
<td>38.7</td>
<td>200,434</td>
<td>Required Barrier Speed Rating</td>
<td>K4</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Car</td>
<td>40.0</td>
<td>107</td>
<td>75.4</td>
<td>38.7</td>
<td>200,434</td>
<td>Required Barrier Speed Rating</td>
<td>K4</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
In order to properly satisfy security requirements, active vehicle barriers such as those depicted above must be capable of operating continuously and with minimal maintenance and downtime.

Prior to implementing active vehicle barriers, the owner / operator must determine whether to allow security staff to operate the barrier from a control room or require that its operation remain near the actual access point. This will be primarily dependent on the security requirements set forth for the dam site based on traffic flow and the availability of security personnel. Backup generators or manual override systems should be in place to operate the barriers in case of a breakdown or power failure.

Another aspect that should be considered to the maximum extent possible is the overall appearance of the barrier. It is important to attempt to assimilate the barrier with the surroundings as much as possible to ensure an aesthetic look. This is more easily accomplished when terrain is incorporated into the barrier design.
Attachment 3: Calculating Kinetic Energy

In the worst case of a head-on impact, the calculation of Kinetic Energy (KE) of a ramming vehicle is \( \frac{1}{2} \times M \times V^2 \), where \( M \) is the vehicle mass, \( V \) is the vehicle velocity.

Note that in U.S. units, the weight in pounds should be divided by 32.2 to get mass. The velocity should be in ft/sec. For example, for a 10,000-lb vehicle travelling at 50 miles per hour, use the following conversions:

- Mass: \( \frac{10,000 \text{ lbs}}{32.2 \text{ ft/sec}^2} = 311 \text{ lb-sec}^2/\text{ft} \)
- Velocity: 50 mph = \( \frac{50 \times (5280 \text{ ft})}{3600 \text{ sec}} = 73.3 \text{ ft/sec} \)
- \( KE = \frac{1}{2} \times M \times V^2 = 836,357 \text{ ft–lb} \)

Some vehicle types and loaded weights are shown in Table A3-1.

### Table A3-1: VBIED Weight/Mass Information

<table>
<thead>
<tr>
<th>Threat</th>
<th>Threat Description</th>
<th>GVWR(^1) Lb</th>
<th>kg</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sedan</td>
<td></td>
<td>5,000</td>
<td>2,300</td>
</tr>
<tr>
<td>Passenger/</td>
<td></td>
<td>10,000</td>
<td>4,500</td>
</tr>
<tr>
<td>Cargo Van</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Mid-Size Truck</td>
<td></td>
<td>35,000</td>
<td>15,900</td>
</tr>
<tr>
<td>Water Truck</td>
<td></td>
<td>66,000</td>
<td>29,900</td>
</tr>
<tr>
<td>Semi-Trailer</td>
<td></td>
<td>80,800</td>
<td>36,700</td>
</tr>
</tbody>
</table>

Notes: Gross Vehicle Weight Rating (GVWR)

Kinetic Energy = \( \frac{1}{2} \times M \times V^2 \)

Divide Weight in lbs by 32.2 to get mass

This guide is published under the auspices of the U.S. Department of Homeland Security (DHS). The need for the guide was identified by the Dams Sector Security Education Workgroup, which is composed of members from the Dams Sector Coordinating Council (SCC) and the Dams Sector Government Coordinating Council (GCC).

The SCC and the GCC were established as a partnership mechanism to collaborate with the DHS Dams Sector–Specific Agency in sector-wide security and protection activities focused on the Dams Sector. For more information, contact: dams@dhs.gov.